

# LM10 Linear magnetic encoder system



## The LM10 is a contactless high-speed linear magnetic encoder designed for use in harsh environments.

The LM10 features a compact sealed readhead that rides at up to 1.5 mm from the self-adhesive magnetic strip scale, which brings up to 100 m travel.

Simple to install, the LM10 features an integral set-up LED on the readhead, wide installation tolerances and an applicator tool for the adhesive-backed magnetic scale. A bidirectional reference is provided that can be either actuated by a preset mark integrated within the scale or by adding a reference sticker on top of the scale with the help of a self aligning installation tool.

The encoders come in digital or analogue output variants and offer a range of customer selectable resolutions including 1, 2, 5, 10, 20, 50 and 100  $\mu\text{m}$ . At 1  $\mu\text{m}$  the LM10 offers a maximum velocity of more than 4 m/s.

Engineered for extreme service, the solid-state LM10 linear encoders operate from  $-20\text{ }^{\circ}\text{C}$  to  $+85\text{ }^{\circ}\text{C}$ , have water-proof sealing to IP68 and are highly resistant to shock, vibrations and pressure. The robust magnetic scale is also resistant to a range of chemicals commonly found in industry.

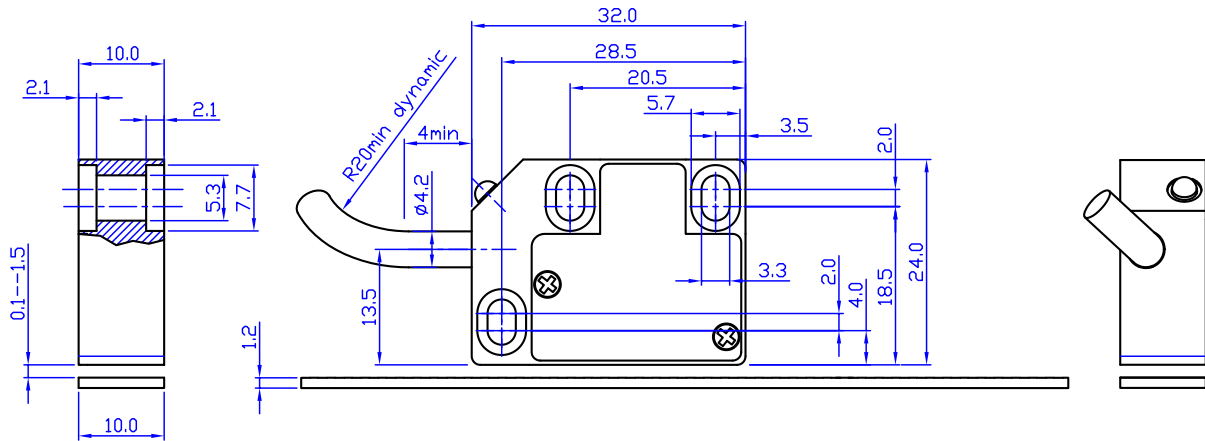
The non-contact, frictionless design eliminates wear while reducing hysteresis for high precision at high speeds and acceleration.

The LM10 encoders bring reliable solutions to tough, hard-working applications including woodworking, stone-cutting, sawing, metalworking, textiles, printing, packaging, plastics processing, automation and assembly systems, laser/flame/water-jet cutting, electronic chip/board production etc.

- Stick-on reference mark
- Customer selectable resolutions from 100 to 1  $\mu\text{m}$
- High speed operation
- Excellent dirt immunity
- Integral set-up LED
- Axis lengths of up to 100 m
- High reliability from proven non-contact sensing technology
- Industry standard digital and analogue output options

### LM10 Dimensions

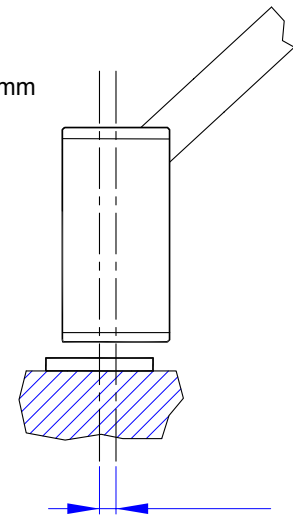
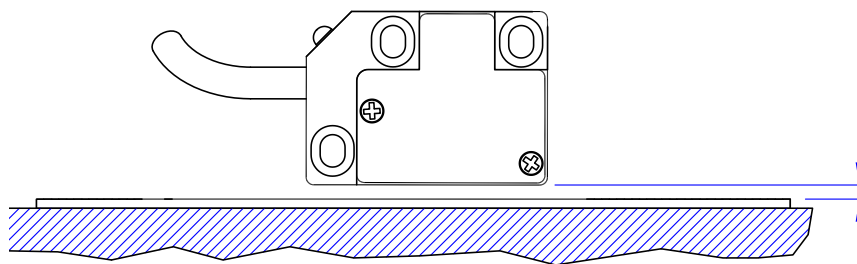
Dimensions and tolerances in mm.



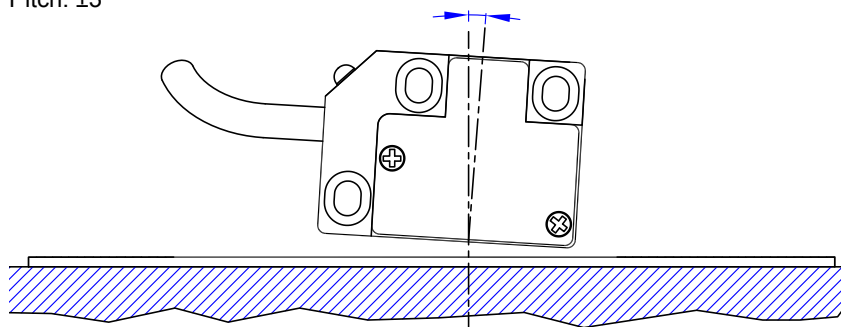
### LM10 Installation tolerances

Ride height: 0.1 to 1.5 mm

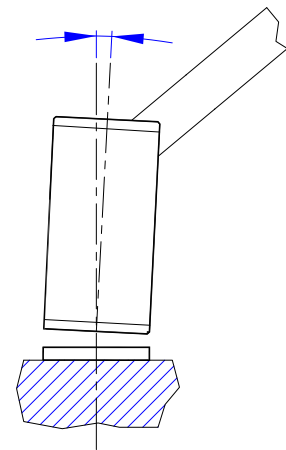
Lateral offset:  $\pm 1.5$  mm



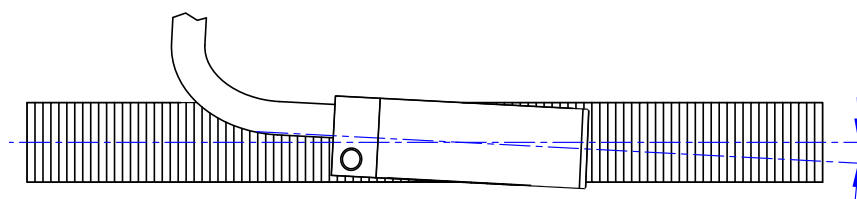
Pitch:  $\pm 3^\circ$



Roll:  $\pm 3^\circ$



Yaw:  $\pm 2^\circ$



## LM10 Technical specifications

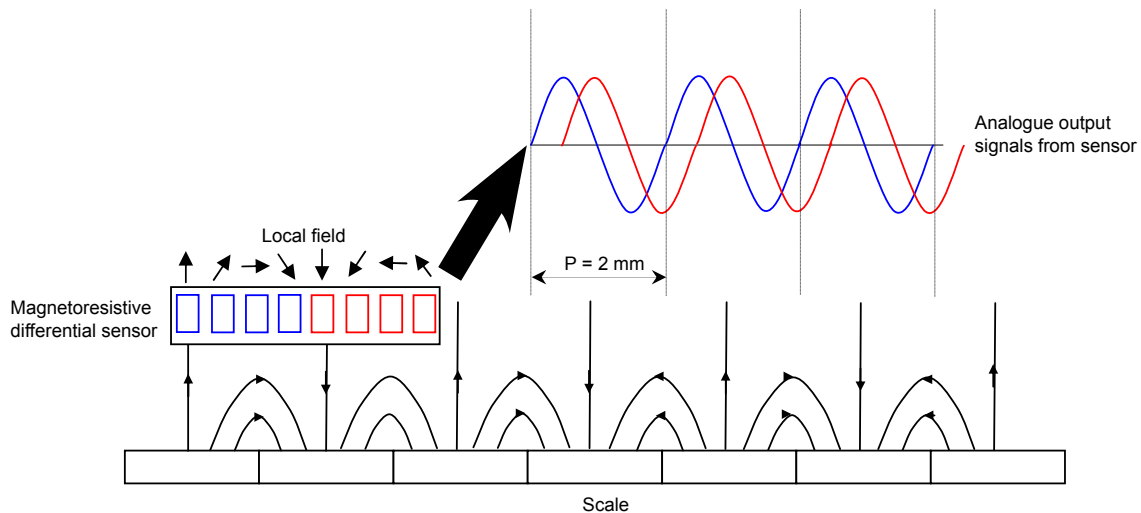
System data																																																													
Maximum measuring length	50 m (100 m special order)																																																												
Pole pitch	2 mm																																																												
Available resolution for digital outputs	1, 2, 5, 10, 20, 50 and 100 $\mu\text{m}$																																																												
Sinusoidal period length	2 mm																																																												
Maximum speed	For sinusoidal output signals: 25 m/s For digital output signals:																																																												
	<table border="1"> <thead> <tr> <th>Resolution (<math>\mu\text{m}</math>)</th> <th colspan="5">Maximum velocity (m/s)</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>4.16</td> <td>1.04</td> <td>0.52</td> <td>0.26</td> <td>0.13</td> </tr> <tr> <td>2</td> <td>8.32</td> <td>2.08</td> <td>1.04</td> <td>0.52</td> <td>0.25</td> </tr> <tr> <td>5</td> <td>20.80</td> <td>5.20</td> <td>2.59</td> <td>1.30</td> <td>0.63</td> </tr> <tr> <td>10</td> <td>25.00</td> <td>10.40</td> <td>5.20</td> <td>2.59</td> <td>1.27</td> </tr> <tr> <td>20</td> <td>25.00</td> <td>10.40</td> <td>5.20</td> <td>2.59</td> <td>1.27</td> </tr> <tr> <td>50</td> <td>25.00</td> <td>6.50</td> <td>3.25</td> <td>1.62</td> <td>0.79</td> </tr> <tr> <td>100</td> <td>25.00</td> <td>25.00</td> <td>25.00</td> <td>25.00</td> <td>20.00</td> </tr> <tr> <td>Edge separation (<math>\mu\text{s}</math>)</td> <td>0.12</td> <td>0.50</td> <td>1</td> <td>2</td> <td>4</td> </tr> <tr> <td>Count frequency (kHz)</td> <td>8333</td> <td>2000</td> <td>1000</td> <td>500</td> <td>250</td> </tr> </tbody> </table>	Resolution ( $\mu\text{m}$ )	Maximum velocity (m/s)					1	4.16	1.04	0.52	0.26	0.13	2	8.32	2.08	1.04	0.52	0.25	5	20.80	5.20	2.59	1.30	0.63	10	25.00	10.40	5.20	2.59	1.27	20	25.00	10.40	5.20	2.59	1.27	50	25.00	6.50	3.25	1.62	0.79	100	25.00	25.00	25.00	25.00	20.00	Edge separation ( $\mu\text{s}$ )	0.12	0.50	1	2	4	Count frequency (kHz)	8333	2000	1000	500	250
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Count frequency (kHz)	8333	2000	1000	500	250																																																								
Sensor/magnetic scale gap	With stick-on reference: 0.5 to 1.5 mm With periodic or machined reference: 0.1 to 1.5 mm																																																												
System accuracy	$\pm 40 \mu\text{m}$ at 20 °C																																																												
Linear expansion coefficient	$(11 \pm 1) \times 10^{-6}/\text{K}$																																																												
Repeatability	Better than $\pm 5 \mu\text{m}$																																																												
Hysteresis	$< 2 \mu\text{m}$																																																												
Sub divisional error	$< 7 \mu\text{m}$ for $< 0.7 \text{ mm}$ ride height $< 15 \mu\text{m}$ for 1 mm ride height $< 30 \mu\text{m}$ for 1.5 mm ride height																																																												
Electrical data																																																													
Power supply	4.5 V to 5.5 V - reverse polarity protected																																																												
Power consumption	$< 30 \text{ mA}$ - without load																																																												
Voltage drop over cable	$\Delta U = 21.4 \times \text{length} \times 10^{-3} [\text{V}]$ - without load																																																												
Output signals	Digital - Differential RS422A, short circuit protected Sinusoidal - Differential 1 $V_{pp}$																																																												
Mechanical data																																																													
Cable	PUR high flexible cable, drag-chain compatible, double-shielded $8 \times 0.05 \text{ mm}^2$ ; durability: 20 million cycles at 20 mm bend radius																																																												
Environmental conditions																																																													
Temperature	Operating -20 °C to +85 °C Storage -40 °C to +85 °C																																																												
Degree of protection	IP68 (according to IEC 60529)																																																												
EMC Immunity	IEC 61000-6-2 (particularity: ESD: IEC 61000-4-2; EM fields: IEC 61000-4-3; Burst: IEC 61000-4-4; Surge: IEC 61000-4-5; Conducted disturbances: IEC 61000-4-6; Power frequency magnet fields: IEC 61000-4-8; Pulse magnetic fields: IEC 61000-4-9)																																																												
EMC Interference	IEC 61000-6-4 (for industrial, scientific and medical equipment: IEC 55011)																																																												
Vibrations (55 Hz to 2000 Hz)	$300 \text{ m/s}^2$ (IEC 60068-2-6)																																																												
Shocks (11 ms)	$300 \text{ m/s}^2$ (IEC 60068-2-27)																																																												

## How it works

A differential magnetoresistive sensor detects the magnetic signature of the magnetised scale. The sensor produces a sine and cosine signal as the sensor moves along the scale. These analogue signals can then be interpolated internally to produce a range of resolutions to 1 µm.

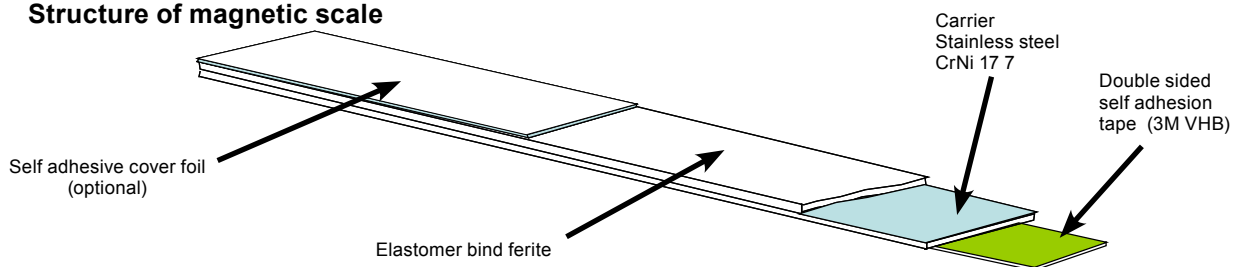
Accurate and reliable reading is obtained by saturating the sensors with flux from the magnetic scale. To achieve this condition the distance between the sensor and the magnetic scale must not exceed 3/4 of the pole pitch. Within this ride height tolerance the Sine/Cosine signals are stable to 10 % signal amplitude.

The sensor detects the magnetic field gradient and is therefore almost insensitive to homogenous stray fields.



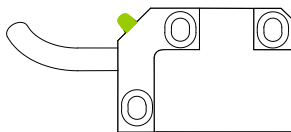
The scale applicator is mounted in place of the readhead and uses the motion of the axis to apply the scale parallel to the guideway. If needed a protective cover strip can also be installed over the magnetic tape.

### Structure of magnetic scale

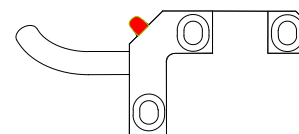


Once installed the readhead can be easily adjusted on the machine using the set-up LED indicator.

Green LED = good signal strength / set-up



Red LED = poor signal strength - adjustment required  
 A, B, A-, B- outputs become high impedance



Readheads can be ordered preset to the required resolution or provided so that they can be programmed as needed on the machine to the chosen resolution. This programming is carried out by connecting the readhead to a computer via a programming interface.

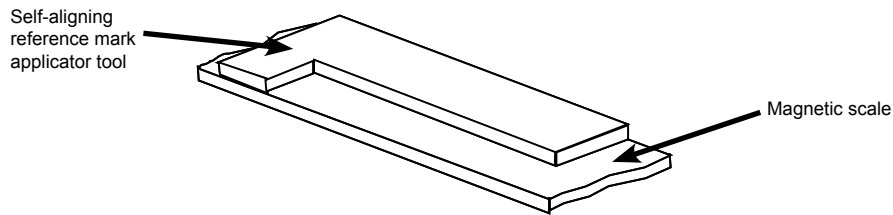
## Reference mark

The repeatable bi-directional reference signal can be provided in 3 ways.

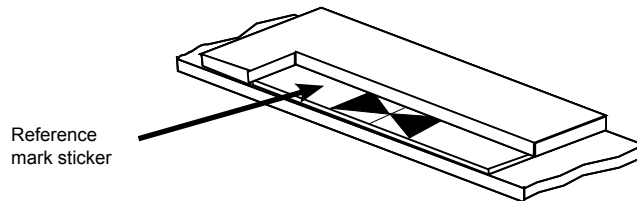
- 1) **Stick-on reference mark.** The LM10 readhead should also have the reference mark option selected. After installation of the scale a reference mark sticker can be applied to the scale at the required position using the reference mark applicator tool. Ensure that the reference sticker is orientated to the corresponding side of the readhead that has the reference mark detector installed.

### Process of installation

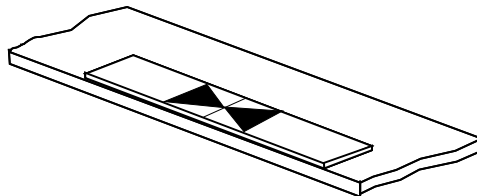
Install scale (+ optional cover strip) – place the reference mark applicator tool on scale in the correct orientation/required position along the length.



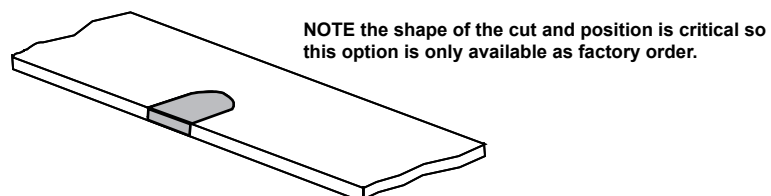
Remove the backing tape from the reference mark sticker and carefully attach it to the surface of the scale by placing it in the recess provided by the applicator tool.



Remove the applicator tool leaving the reference mark sticker in the desired position.



- 2) **Selected at point of order.** The LM10 readhead should also have the reference mark option selected. If required the cover foil can be installed over the cut reference mark.



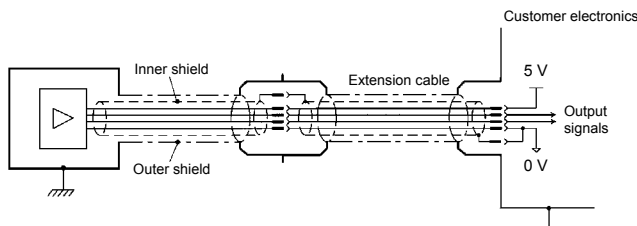
- 3) **Every 2 mm** – the LM10 readhead should be ordered with this specific mode activated only.

## Digital output signals

Square wave differential line driver to EIA RS422

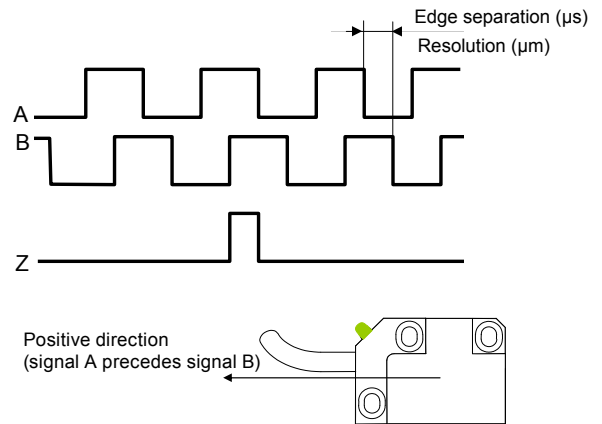
<b>Power supply voltage</b>	4.5 V to 5.5 V Reverse polarity protection
<b>Incremental signals</b>	2 square-wave signals A, B and their inverted signals A-, B-
<b>Reference mark signal</b>	1 or more square-wave pulse Z and its inverted pulse Z-
<b>Signal level</b>	Differential line driver to EIA standard RS422: $U_H \geq 2.5 \text{ V}$ at $-I_H = 20 \text{ mA}$ $U_L \leq 0.5 \text{ V}$ at $I_L = 20 \text{ mA}$
<b>Permissible load</b>	$Z_0 \geq 100 \ \Omega$ between associated outputs $I_L \leq 20 \text{ mA}$ max. load per output Capacitive load $\leq 1000 \text{ pF}$ Outputs are protected against short circuit to 0 V and to +5 V
<b>Alarm</b>	High impedance on output lines A, B, A-, B-
<b>Switching time (10 to 90 %)</b>	$t_+$ , $t_- < 30 \text{ ns}$ (with 1 m cable and recommended input circuit)
<b>Cable</b>	Double shielded PUR cable; max. 100 m

## Electrical connections

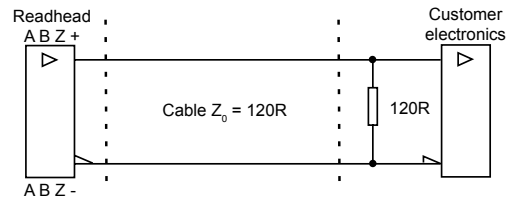


## Timing diagram

(Complementary signals not shown)



## Recommended signal termination



## Connections

Function	Signal	Colour	15 pin D type male	9 pin D type male
Power	5 V	Brown	7	5
	0 V	White	2	9
Incremental signals	A+	Green	14	4
	A-	Yellow	6	8
	B+	Blue	13	3
	B-	Red	5	7
Reference mark	Z+	Pink	12	2
	Z-	Grey	4	6
Shield	Inner	Green/ Yellow	15	1, 9
	Outer	-	Case	Case



# Contact information

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## Document revision details

Issue	Date	Page	Corrections made
02	29.11.2007	-	Minor text errors corrected, Corrected Maximum speed table data on page 3
02	30.11.2007	2	Changed Pitch and Yaw description and image layout

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